

# PaCHash: Packed and Compressed Hash Tables

**SIAM Symposium on Algorithm Engineering and Experiments (ALENEX 23)**

*Florian Kurpicz, Hans-Peter Lehmann and Peter Sanders*

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# Motivation

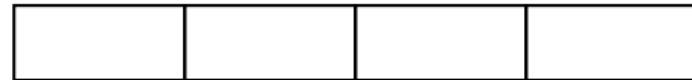
## Setting

- static hash table for objects of variable size
- storing objects in external memory
- ideally retrieve objects in single I/O
- very small internal memory data structure

## Objects of Variable Size



## External Memory



- only blocks of size  $B$  bits can be transferred
- one I/O per block transfer

# Space-Efficient Object Stores from Literature

- objects of size 256 bytes
- blocks of size 4096 bytes
- internal space  $I_b$  (bits/block)
- (\*) consecutive I/O

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	Method	$I_b$	load factor	I/Os
fixed	Larson et al. [LR85]	96	<96 %	1
	SILT SortedStore [Lim+11]	51	100 %	1
	Linear Separator [Lar88]	8	85 %	1
	Separator [GL88; LK84]	6	98 %	1
	Robin Hood [Cel88]	3	99 %	1.3
	Ramakrishna et al. [RT89]	4	80 %	1
	Jensen, Pagh [JP08]	0	80 %	1.25
	Cuckoo [Aza+94; Pag03]	0	<100 %	2
	<b>PaCHash</b> , $a = 1$	2	100 %	2*
variable	<b>PaCHash</b> , $a = 8$	5	100 %	1.13*
	SILT LogStore [Lim+11]	832	100 %	1
	SkimpyStash [DSL11]	32	$\leq 98 \%$	8
	<b>PaCHash</b> , $a = 1$	2	99.95 %	2.06*
	<b>PaCHash</b> , $a = 8$	5	99.95 %	1.19*

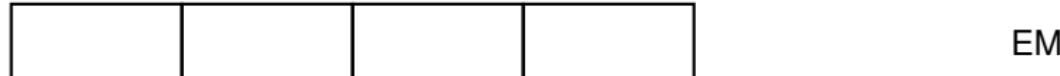
# PaCHash Overview



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1 2 3 4 5 6 7 8 9 10 11 12 hash function  $h: K \rightarrow 1..am$



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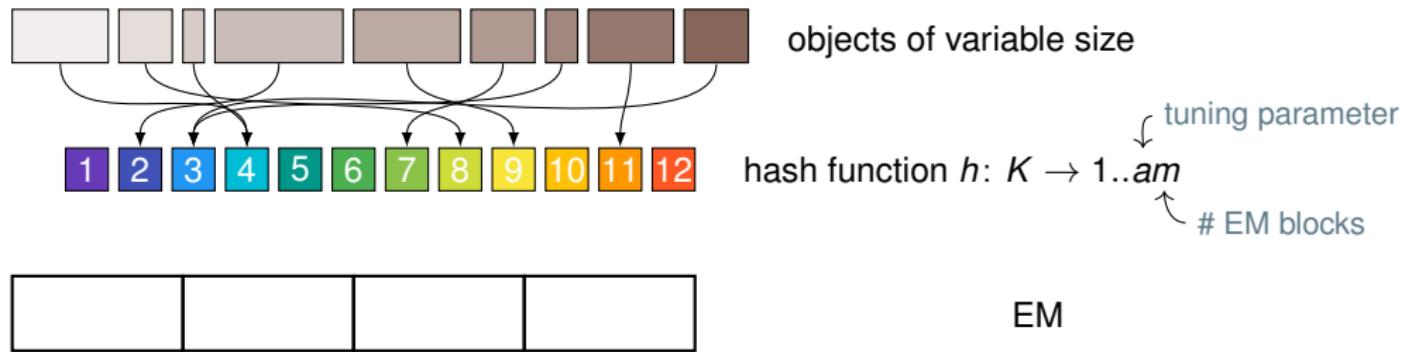
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tuning parameter  
 $\downarrow$   
 # EM blocks  
 $\uparrow$

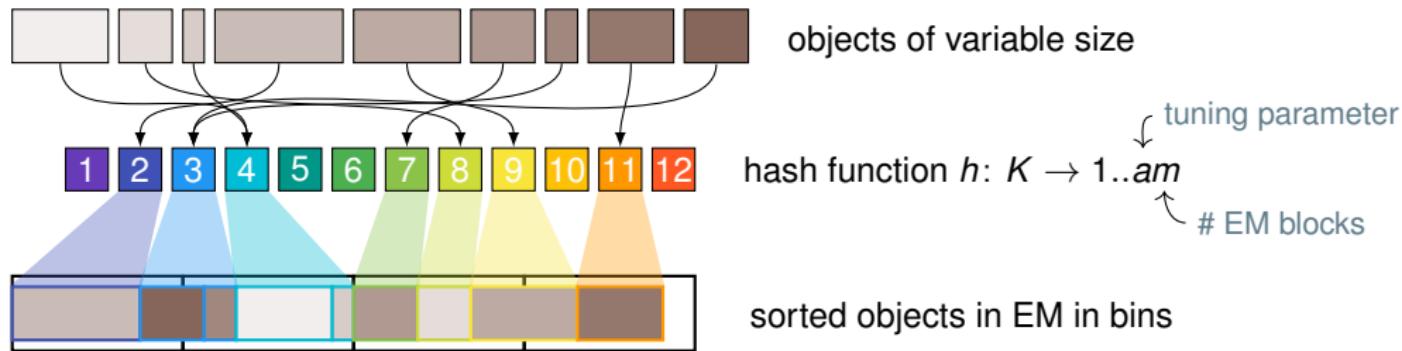


EM

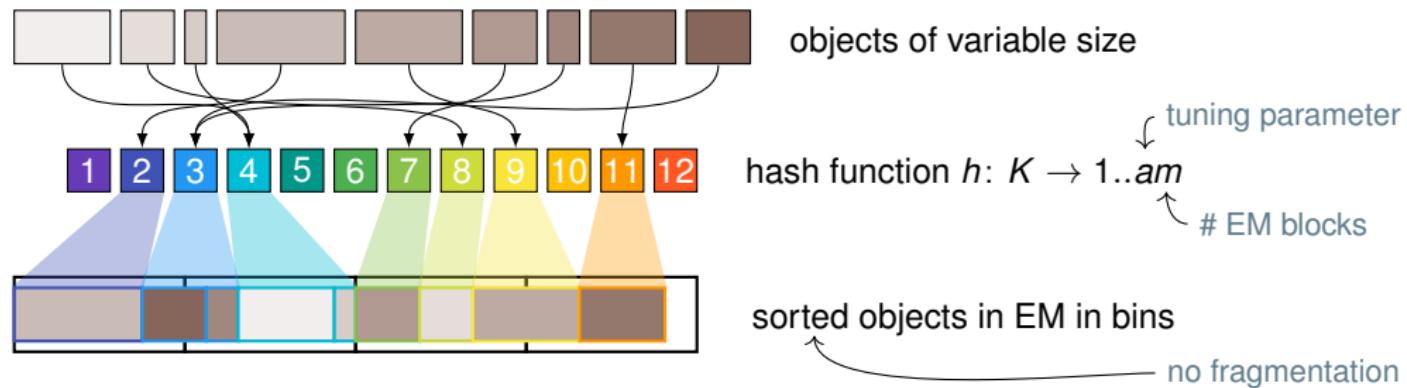
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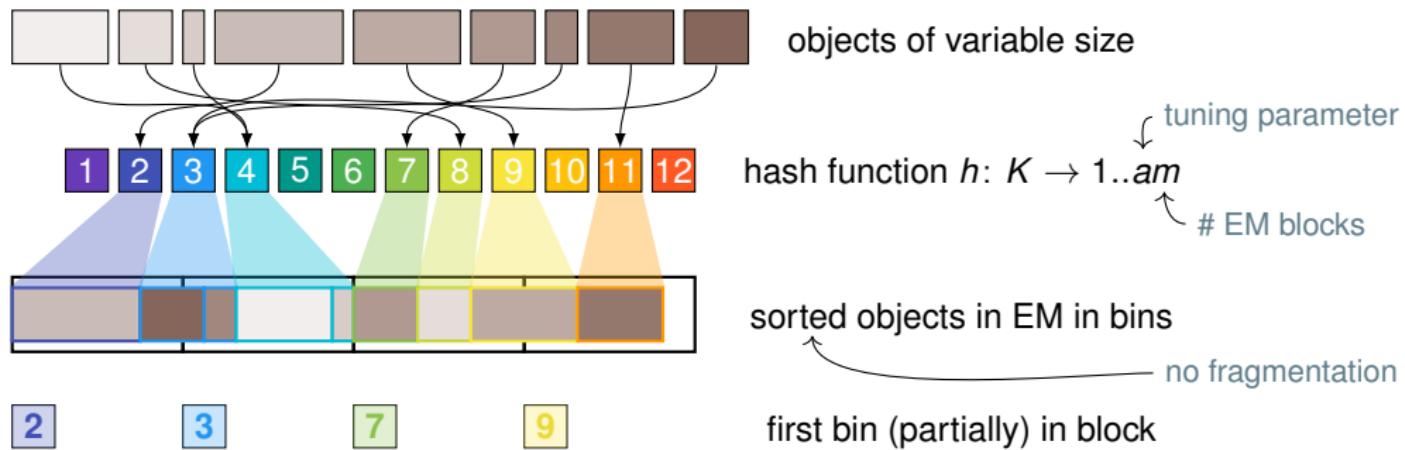
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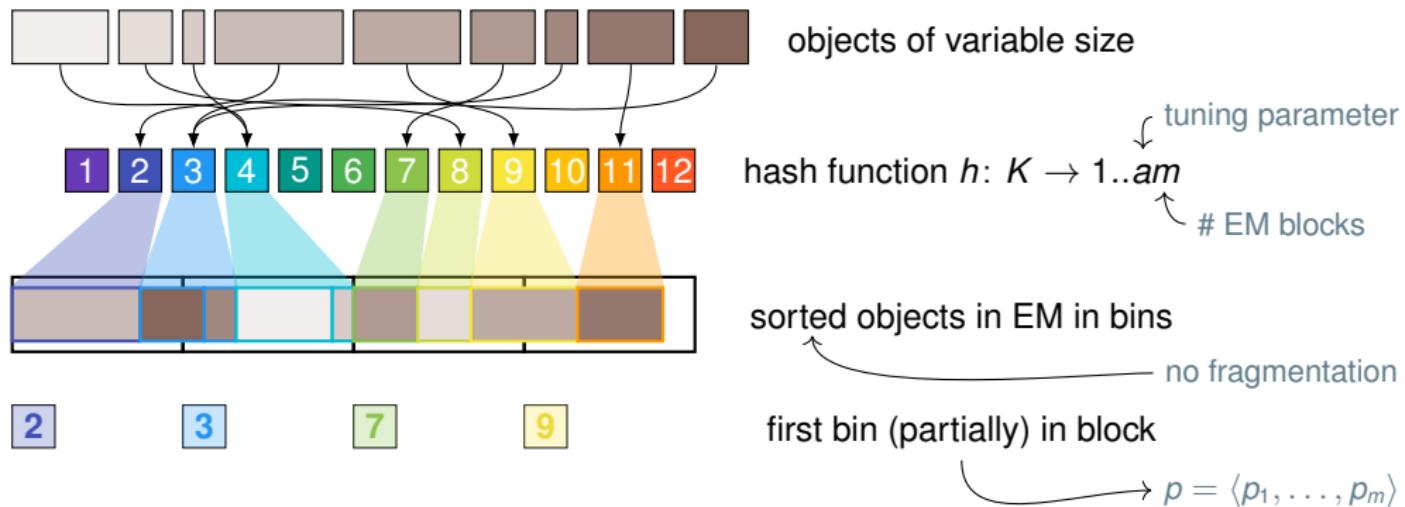
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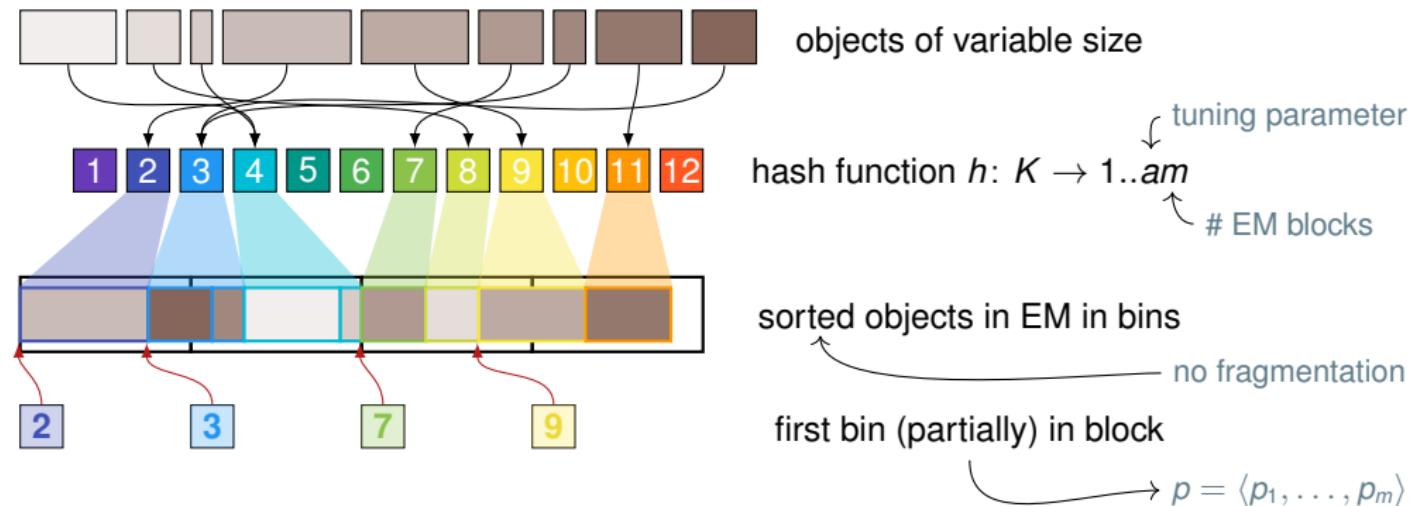
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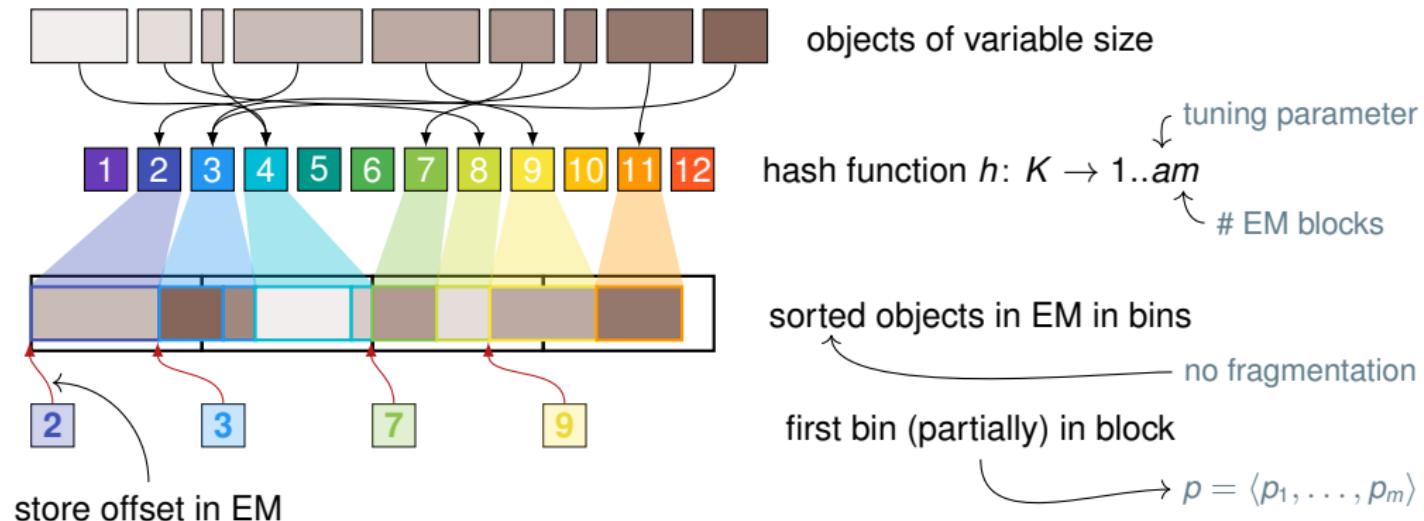
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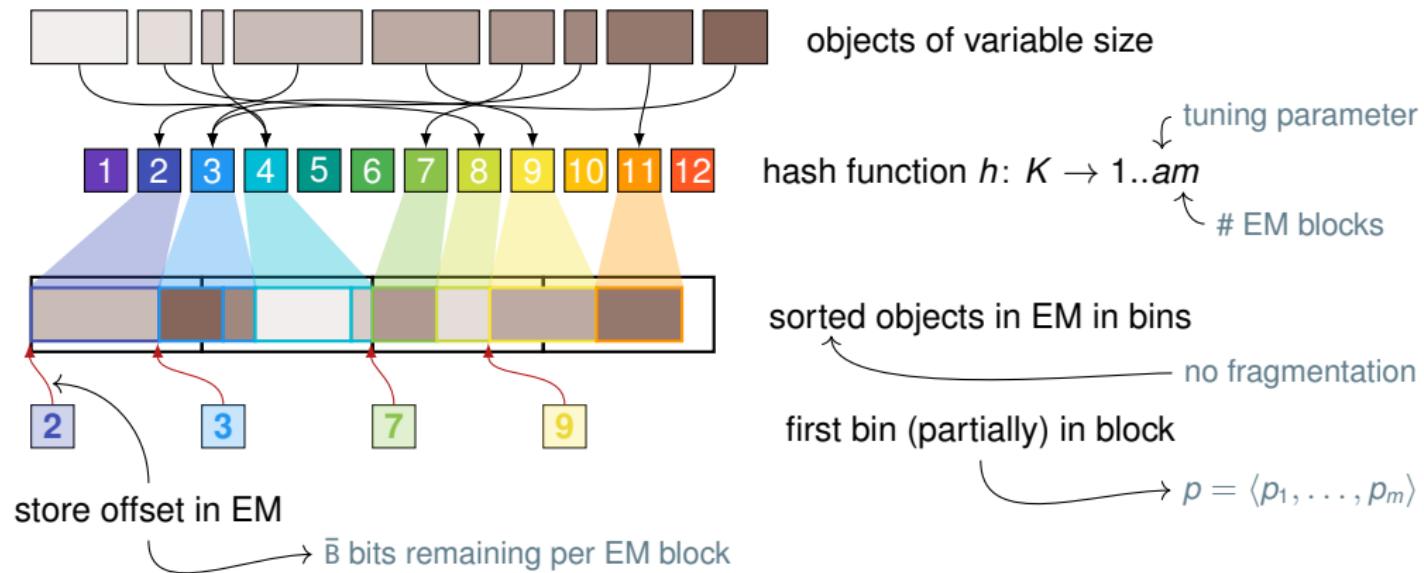
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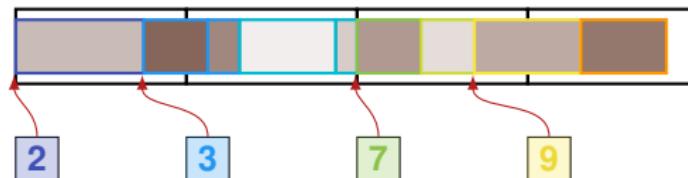


# PaCHash Overview



# Finding Blocks

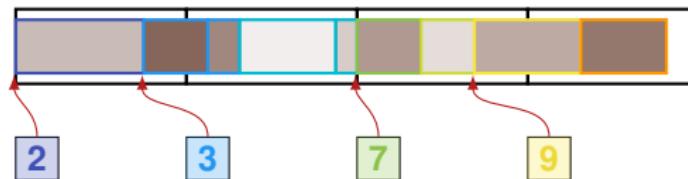
## Query Algorithm



- $b_x = h(x)$
- find first  $i$  with  $p_i \leq b_x$
- if  $p_i = b_x$  let  $i = i - 1$
- find first  $j$  with  $p_j > b_x$
- return  $i..(j - 1)$

# Finding Blocks

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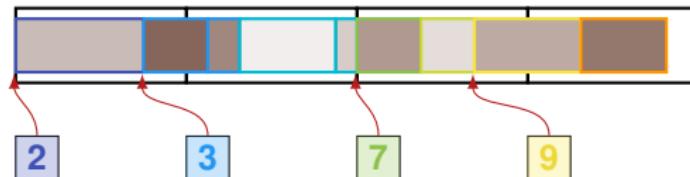
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## Elias-Fano Coding

- given  $k$  monotonic increasing integers in  $1..u$ 
  - store  $\log k$  MSBs encoded in bit vector
  - store  $\log(u/k)$  LSBs plain
  - $k(2 + \log(u/k)) + 1 + o(k)$  bits in total
- predecessor in  $O(k)$  time

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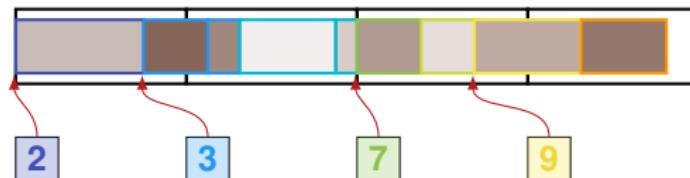
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### Lemma: Space with Elias-Fano Coding

When using Elias-Fano coding [Eli74; Fan71] to store  $p$ , the index needs  $2 + \log a + o(1)$  bits of internal memory per block.

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# Predecessor Query in PaCHash Internal Memory

## Lemma: Expected Predecessor Time

When using Elias-Fano coding to store  $p$ , the range of blocks containing the bin of an object  $x$  can be found in expected constant time.

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- consider  $\lceil \log m \rceil$  MSB
- let bin  $b_x$  have MSBs equal to  $u$
- expected size  $\mathbb{E}(Y_u)$  of all bins with MSB  $u$  that are  $< b_x$  is

$$\begin{aligned}
 & \sum_{y \in S} |y| \cdot \mathbb{P}(h(y) \text{ w/ MSB } = u; h(y) < h(x)) \\
 & \leq \sum_{y \in S} |y| \cdot \mathbb{P}(h(y) \text{ w/ MSB } = u) \\
 & = \frac{1}{m} \sum_{y \in S} |y| = \frac{m\bar{B}}{m} = \bar{B}
 \end{aligned}$$

- number of entries to scan is  $\mathbb{E}(Y_u)/\bar{B} = 1$

# Loading Blocks from External Memory

## Lemma: Additional Blocks Loaded

Retrieving an object  $x$  of size  $|x|$  from a PaCHash data structure loads  $\leq 1 + |x|/\bar{B} + 1/a$  consecutive blocks from the external memory in expectation.

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$$\begin{aligned}\mathbb{E}(|b_x|) &= |x| + \sum_{y \in S, y \neq x} |y| \mathbb{P}(y \in b_x) \\ &\leq |x| + \sum_{y \in S} |y| \mathbb{P}(y \in b_x) \\ &= |x| + \sum_{y \in S} |y| \cdot \frac{1}{am} = |x| + \frac{\bar{B}}{a}\end{aligned}$$

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 \end{aligned}$$

- expected number of blocks overlapped by  $b_x$

$$\begin{aligned}
 \mathbb{E}(X) &= 1 + (\mathbb{E}(|b_x|) - 1)/\bar{B} \\
 &= 1 + \frac{|x|}{\bar{B}} + \frac{1}{a} - 1/\bar{B}
 \end{aligned}$$

- $\mathbb{P}(\text{bin and block border align}) = 1/\bar{B}$

# Experimental Evaluation

## Hardware and Software

- Intel i7 11700 (base clock speed: 2.5 GHz)
- 1 TB Samsung 980 Pro NVMe SSD
- Ubuntu 21.10 (Kernel 5.13.0)
- io\_uring for I/O operations
- GCC 11.2.0 (-O3 -march=native)
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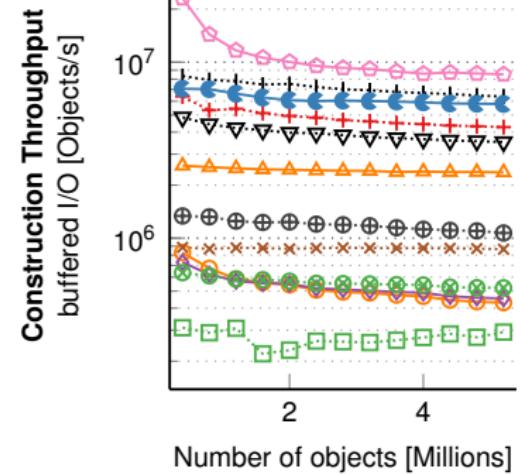
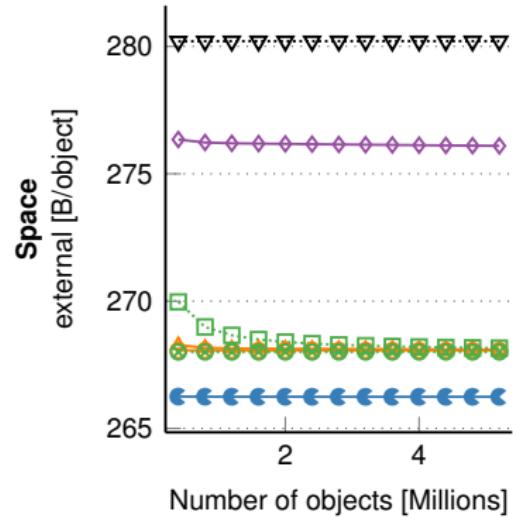
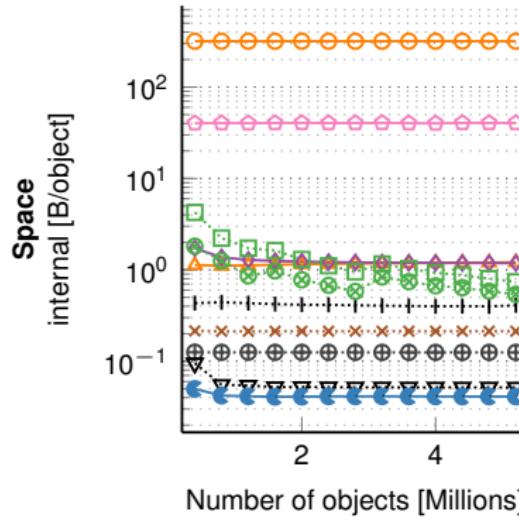
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## Competitors

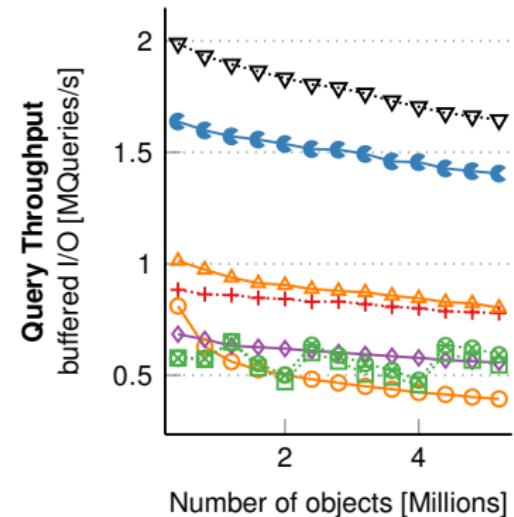
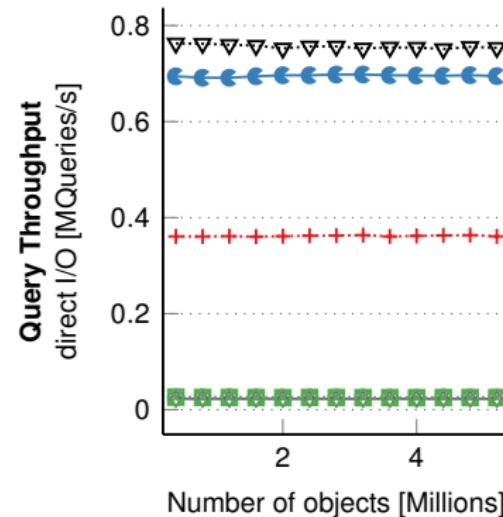
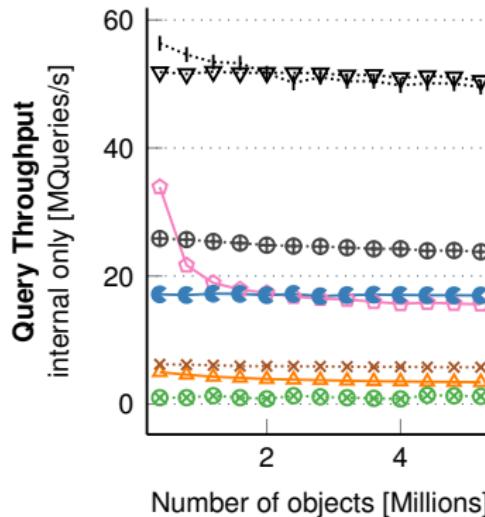
- LevelDB [[Goo21](#)]
- RocksDB [[Fac21](#)]
- SILT [[Lim+11](#)].
- `std::unordered_map`
- RecSplit [[EGV20](#)]
- CHD [[BBD09; CR+12](#)]
- PTHash [[PT21](#)]

# Construction



- ⊕ CHD (16-perfect) [BB09]
- + Cuckoo (here)
- △ LevelDB (Static part) [Goo21]
- LevelDB [Goo21]
- PTHash [PT21]
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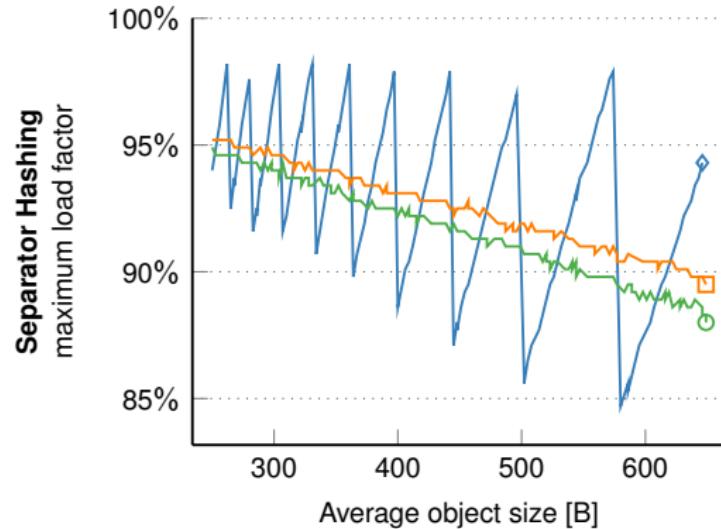
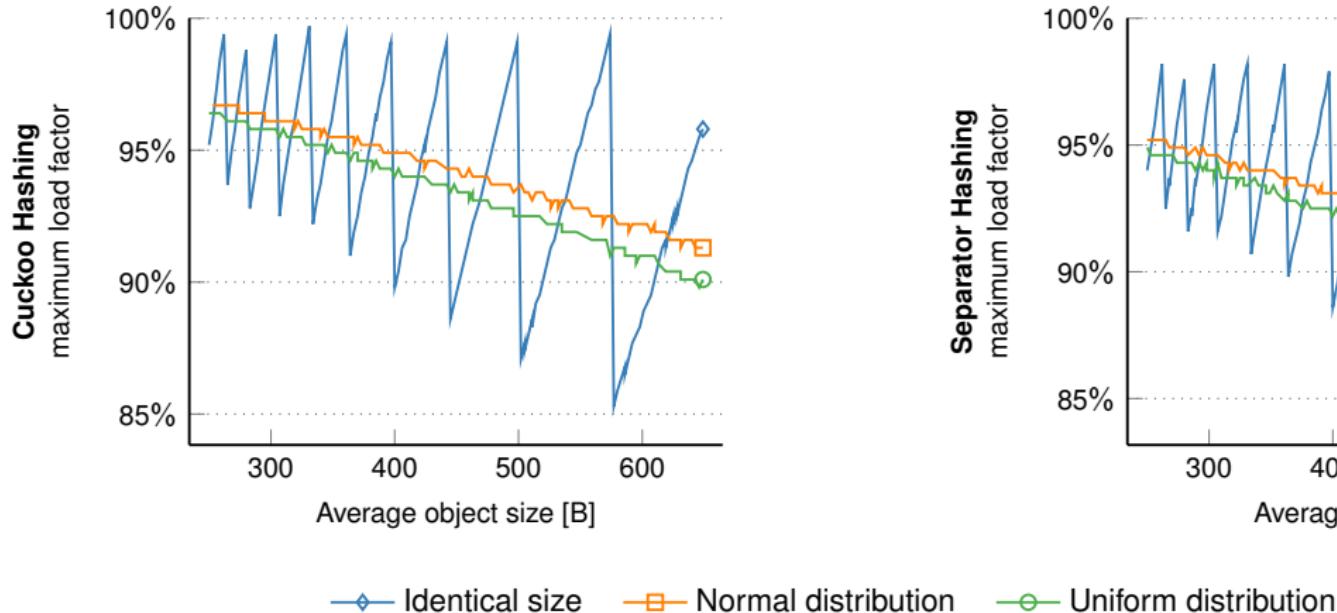
# Queries



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# Maximum Load Factor of Competitors



# Alternative Internal Memory Data Structures

## Lemma: Space with Succincter

When using Succincter [Pat08] to store  $p$ , the index needs  $1.44 + \log(a + 1) + o(1)$  bits of internal memory per block.

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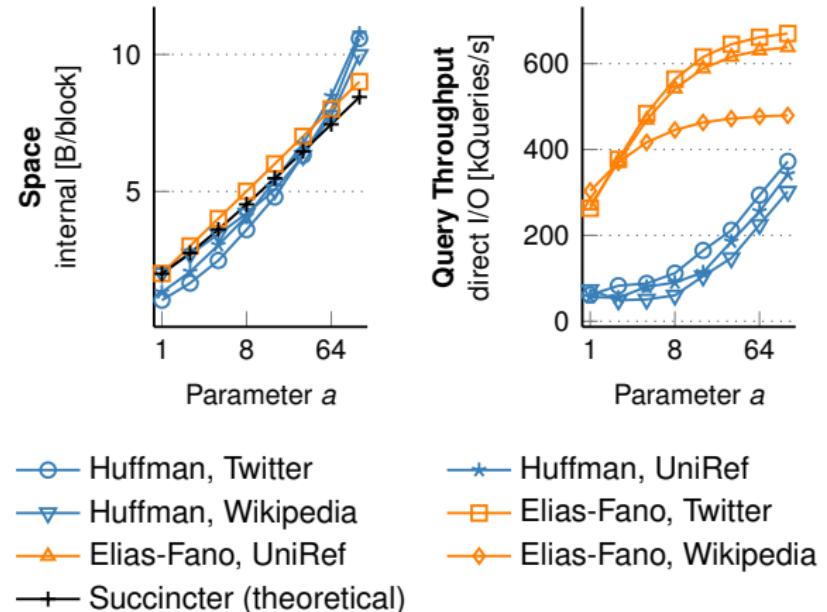
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# Conclusion

- static hash table for objects of variable size
  - constant number of bits per EM block
  - outperforming competitors (variable size)
  - matching/outperforming competitors (fixed size)
- 
- code available under GPLv3 license
  - <https://github.com/ByteHamster/PaCHash>
  - check it out ☺



European Research Council  
Established by the European Commission

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