On Maximum Common Subgraph Problems in Series-Parallel Graphs

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Definition (Series-Parallel Graphs (SPGs))

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Lemma [Brandstadt et al., 1999]

G is series-parallel \iff G is a partial 2-tree.



The Complexity of the Problem



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- ▶ Trees in P [Matula, 1978]
- Outerplanar with bounded degree in P [Akutsu & Tamura, 2013]

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- 1. Proof of NP-hardness if degree is not bounded for all vertices.
- 2. Polynomial time algorithm for restricted feasible solutions.

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Theorem [Gupta & Nishimura 1994]

SI in partial k-trees with degree $\leq k+2$ for all but k vertices is in **NPC**.

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Theorem [Gupta & Nishimura 1994]

SI in SPGs with degree ≤ 4 for all but 2 vertices is in NPC.

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    MCIS<sup>\leq3,1</sup>: NP-hard \rightarrow now
```

Kriege, Kurpicz, Mutzel

Definition (Numerical Matching with Target Sums (NMwTS))

Input: Two multisets of integers X and Y with |X| = |Y| = n and a vector $\vec{b} = \langle b_1, \dots, b_n \rangle$ with $b_i \in \mathbb{N}_0$ for all $i = 1, \dots, n$.

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2

6

 \vec{b}

4

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 \vec{b} 2+1=3 3+3=6 1+1=2 1+3=4 4+2=6 3+4=7







Definition (NP-complete in the strong sense) [Garey & Johnson 1979]
▶ NPC in the strong sense ↔ NPC with unary encoded input.



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- ▶ NPC in the strong sense ↔ NPC with unary encoded input.
- ► NMwTS is **NPC** in the strong sense.

Construction of the Reduction

Outline for each NMwTS-Instance (X, Y, s, \vec{b})

- Represent X, Y and \vec{b} as graphs G and H.
- ► Size of MCIS indicates type of instance.

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Parts of the Graphs

- 1. Base-Gadgets \rightarrow Structure of the MCIS.
- 2. Encoding of the sizes of X,Y and $\vec{b} \rightarrow$ Size of the MCIS.





• \bar{x}, \bar{y} with unbounded degree.



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• Cycles: $2\sum_{z \in X \cup Y} v(z) + 2$ vertices.







Encode the Sizes of \boldsymbol{X} and \boldsymbol{Y}



Encode the Sizes of \vec{b}



- Entries of b
- +1 to compensate the separating paths

Theorem

MCIS in SPGs with degree ≤ 3 for all but 1 vertex is **NP**-hard.





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 (X,Y,s,\vec{b}) is a Yes-Instance $\iff \mathsf{MCIS}(G,H) = |V(G)| - 2n + 1$ = |V(H)| - 2n + 1





▶ $|V(G)| = |V(H)| \rightarrow \text{Base-Gadgets & Encoding.}$

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- ▶ $|V(G)| = |V(H)| \rightarrow \text{Base-Gadgets & Encoding.}$
- n-1 missing vertices in the base-gadget.

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A Polynomial Time Algorithm

Definition (k-Maximum Common Subgraph (k-MCS))

Input: *k*-connected partial *k*-trees *G*, *H*.

Output: Maximum common k-connected subgraph of G and H.

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Known Variants of k-MCS in P

1-MCS ⇔ Maximum Common Subtree Problem ✓ [Matula, 1978] 2-MCIS in SPGs ✓ [Kriege & Mutzel, 2014]

Graph Decomposition

Definition (BC-Tree)

- Tree consisting of a node for each cut vertex and block.
- Distinguish between bridges and non-bridge blocks.
- Edges between nodes if cut vertex is contained in block.



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- BC-tree is bipartite with respect to cut vertices and blocks.
- ▶ Non-bride blocks represent 2-connected SPGs.

Fewer Restrictions

Definition (Block-and-Bridge Preserving MCS (BBP-MCS))

- ► Variant of the general common subgraph problem [Schietgat et al., 2007]
- Non-Bridge blocks are only mapped onto non-bridge blocks.
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- Only compare blocks of the same type.
- ► There is an algorithm for 2-MCIS.

Idea of the Algorithm

Edmonds-Matula Algorithm for 1-MCS (Sketch)

- 1. Decompose trees into rooted subtrees.
- 2. Compute MCS of subtrees (Maximum Weighted Bipartite Matching).
- 3. Combine partial solutions.

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Algorithm for BBP-MCIS (Sketch)

- 1. Decompose BC-trees into rooted BC-subtrees.
- 2. Compute MCS of subgraphs represented by subtrees:
 - Maximum Weighted Bipartite Matching
 - \blacktriangleright Extended 2-MCIS algorithm \rightarrow work with cut vertices
- 3. Combine partial solutions.

The root is a vertex in the input graph.

A subgraph can now be induced by a BC-subtree.



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Proof (Sketch)

- (Extended) 2-MCIS can be solved in $\mathcal{O}(n^6)$.
- ► Comparison of all blocks at cut vertices in $\mathcal{O}(n^5) \rightarrow \text{at most } \mathcal{O}(n^2)$ pairs of cut vertices and MWBM is solvable in $\mathcal{O}(n^3)$.
- ▶ Total time $\rightarrow \mathcal{O}(n^6)$.

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Proof (Sketch)

- (Extended) 2-MCIS in outerplanar graphs can be solved in $\mathcal{O}(n^3)$.
- Comparison of all blocks stays expensive.

- **NP**-hardness of MCIS in SPGs with one vertex of unbounded degree.
- ▶ BBP-MCIS in SPGs can be solved in polynomial time.

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Open Questions

- Complexity of MCS in SPGs with bounded degree?
- Edge-Disjoint-Path Problem in SPGs is in NPC. [Nishizeki et al., 2001]

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